

1 **Evaluating the role of data quality when sharing information in hierarchical**
2 **multi-stock assessment models, with an application to dover sole**

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8 **Abstract**

9 An emerging approach to data-limited fisheries stock assessment uses hierarchical
10 multi-stock assessment models to group stocks together, sharing information from data-rich
11 to data-poor stocks. In this paper, we simulate data-rich and data-poor fishery and survey
12 data scenarios for a complex of dover sole stocks. Simulated data for individual stocks were
13 used to compare estimation performance for single-stock and hierarchical multi-stock
14 versions of a Schaefer production model. The single-stock and best performing multi-stock
15 models were then used in stock assessments for the real dover sole data. Multi-stock
16 models often had lower estimation errors than single-stock models when assessment data
17 had low statistical power. Relative errors for productivity and relative biomass parameters
18 were lower for multi-stock assessment model configurations. In addition, multi-stock
19 models that estimated hierarchical priors for survey catchability performed the best under
20 data-poor scenarios. We conclude that hierarchical multi-stock assessment models are
21 useful for data-limited stocks and could provide a more flexible alternative to data-pooling
22 and catch only methods; however, these models are subject to non-linear side-effects of
23 parameter shrinkage. Therefore, we recommend testing hierarchical multi-stock models in
24 closed-loop simulations before application to real fishery management systems.

25 December 29, 2018

Introduction

Fisheries stock assessment modeling uses catch and abundance monitoring data to estimate the status and productivity of exploited fish stocks (Hilborn 1979). Despite improvements in catch monitoring and increasing prevalence and quality of fishery-independent surveys of abundance, many fisheries remain difficult to assess because the data lack sufficient statistical power to estimate key quantities necessary for management (Peterman 1990). Low power data may arise, for example, because time-series are short relative to the productivity cycles of exploited fish stocks, historical fishing patterns may be weak or uninformative, and monitoring data may simply be too noisy to extract biomass and productivity signals (Magnusson and Hilborn 2007). Where these situations occur, stocks are often deemed *data-limited* (MacCall 2009; Carruthers et al. 2014).

An emerging approach to fisheries stock assessment is to use a hierarchical approach to assess data-limited stocks simultaneously with data-rich stocks. Data-limited stocks can “borrow information” from data-rich stocks, providing a compromise between data-intensive single-stock assessments and problematic data-pooling approaches (Jiao et al. 2009, 2011; Punt et al. 2011). The hierarchical multi-stock approach, which shares information between data-rich and data-poor stocks, treats multiple stocks of the same species as replicates that, to varying degrees, share environments, life history characteristics, ecological processes, and fishery interactions (Peterman et al. 1998; Punt et al. 2002; Malick et al. 2015). Information present in the observations for data-rich replicates is shared with more data-poor replicates via hierarchical prior distributions on parameters of interest (Punt et al. 2011; Thorson et al. 2015). Sharing information in this way could improve scientific defensibility of assessments for data-limited stocks, because stock status and productivity estimates are informed by data rather than strong *a priori* assumptions on population dynamics parameters.

Information-sharing properties of hierarchical models are realized as the shared hierarchical priors induce shrinkage of estimated parameters towards the overall prior mean (Carlin and Louis 1997; Gelman et al. 2014). Although shrinkage can reduce bias in the presence

of high uncertainty (e.g. very data-limited stocks), it may also increase bias for data-rich replicates by pulling estimated parameters closer to the group mean. Shrinkage properties are well understood for hierarchical linear models (James and Stein 1961; Raudenbush and Bryk 2002), including those applied in fisheries. For example, when estimating productivity of Pacific salmon stocks, hierarchical Ricker stock-recruitment models are more successful at explaining variation in stock productivity when stocks are grouped at scales consistent with climatic variation (Peterman et al. 1998; Mueter et al. 2002). It is unclear, however, whether the benefits observed for linear models extend to iteroparous groundfish stocks, for which productivity parameters are deeply embedded within non-linear population dynamics and statistical models.

Parameter shrinkage has been observed in stock assessments for data-limited groundfish and shark species when grouped with data-moderate species (Jiao et al. 2009, 2011; Punt et al. 2011), but it is unknown whether such shrinkage in reality increases or decreases bias in parameter estimates. Simulation tests of the hierarchical multi-stock approach to age-structured assessments revealed that bias reductions in one species often induce greater bias for others in the assessment group, indicating that shrinkage could imply unwanted trade-offs (Punt et al. 2005).

In this paper, we used a simulation approach to investigate relationships between hierarchical model structure, bias, and precision for hierarchical multi-stock Schaefer stock assessment models. For the hierarchical multi-stock models, we defined shared prior distributions on survey catchability and optimal harvest rate (productivity) and then identified combinations of shared priors that produced the most reliable estimates of key management parameters when fit to simulated data from high and low data quality multi-stock complexes. Best performing single and multi-stock models were then applied to real data for a dover sole complex in British Columbia, Canada.

Methods

We simulated a multi-stock complex representing the dover sole (*Microstomus Pacificus*) fishery in British Columbia, Canada. Dover sole stocks were simulated under low to high data quality (statistical power) scenarios. Under each scenario, bias and precision metrics were determined for key management parameters under both single-stock and hierarchical multi-stock Schaefer models. In our hierarchical multi-stock assessment models shared evolutionary history and a common scientific survey influenced our choice of shared prior distributions. For example, stocks that share evolutionary history may have similar productivity at low stock sizes (Jiao et al. 2009, 2011), and a common trawl survey may induce correlations in catchability (trawl efficiency) observation errors.

Study system

British Columbia's dover sole complex is divided into three distinct but connected stocks (Figure 1), distributed along the BC coast from the northern tip of Haida Gwaii, south through Hecate Strait into Queen Charlotte Sound, and on the west coast of Vancouver Island. Although the dover sole fishery has operated since 1954, prior to 1970 it was very limited, increasing to present levels by the late 1980's (Figure 2).

Despite a long history of exploitation, dover sole stocks have never been evaluated using model-based assessments. No observational data exists for the Queen Charlotte Sound (QCS) and west coast of Vancouver Island (WCVI) stocks prior to 2003, precluding a model based assessment before that time (Fargo 1999). The Haida Gwaii and Hecate Strait (HS) stock was surveyed from 1984 - 2003 (Figure 2, Survey 1), but data was only used to perform catch curve analyses for total mortality rate estimates (Fargo 1998). During 1984 - 2003, a fine-mesh trawl survey was used for the Vancouver Island stock and a portion of the Hecate Strait stock, but the survey was not designed for groundfish and produced stock indices that were highly variable. Since 2003, a new bottom trawl survey has operated coast-wide, which

samples all three stocks (Figure 2, Survey 2), but no assessment has been performed in that time.

Dover sole may be suitable for a hierarchical multi-stock assessment for 3 main reasons. First, the Hecate Strait stock has longer series of informative data than the other stocks, potentially providing information for the other two stocks. Second, modeling a single-species makes it likely that stock productivities and responses to the environment are similar. Lastly, all stocks are observed by Survey 2, making it likely that the observation model parameters for each stock are similar for that survey. By applying the hierarchical multi-stock approach, the similarities between stocks may be exploited to the benefit of the whole complex, extending model based stock assessments for dover sole for the first time.

Simulation Framework

Our simulation framework was composed of an operating model that simulated biological dynamics, catch, and observational data, and an assessment model that performed both single-stock and hierarchical multi-stock assessments from the simulated data. Both operating and assessment models used a process-error Schaefer formulation for biomass dynamics, where the biomass in each year is deviated from the expected value using a log-normal process error term. This choice allowed us to focus on the effects of hierarchical estimation and shrinkage without confounding among hierarchical priors and the model structure. We used the R statistical software package to specify the operating model, and the Template Model Builder (TMB) package to specify the assessment model ([R Core Team 2015](#); [Kristensen et al. 2015](#)).

The simulation approach is described below in 3 main sections (i) the operating model, (ii) assessment models, and (iii) simulation experiments. The next section describes the operating model structure, including process errors, and how catch and survey observations were generated. Assessment models are then outlined, with details of the shared hierarchical prior distributions given in the supplemental material. Finally, we present the experimental

129 design and performance metrics for the simulations.

130 **Operating model**

131 We simulated biomass dynamics for each stock s in our assessment complex on an annual
132 time step t , using the process-error Schaefer model ([Punt 2003](#))

$$B_{s,t+1} = (B_{s,t} + r_s B_{s,t} (1 - B_{s,t}/B_{s,0}) - C_{s,t}) e^{\epsilon_{s,t}}, \quad (1)$$

133 where $B_{s,t}$ is the biomass of stock s at time t , r_s is the intrinsic rate of increase, $B_{s,0}$ is the
134 unfished equilibrium biomass, and $\epsilon_{s,t}$ is the process error deviation for stock s at time t .
135 Schaefer model process error deviations $\epsilon_{s,t}$ were decomposed via the sum of a shared (across
136 stocks) mean year-effect $\bar{\epsilon}_t$, and a correlated (among stocks) stock-specific effect $\zeta_{s,t}$, which
137 is the s component of the vector $\zeta_{\cdot,t}$, that is,

$$\epsilon_{s,t} = \bar{\epsilon}_t + \zeta_{s,t},$$

$$\bar{\epsilon}_t \sim N(0, \kappa),$$

$$\zeta_{\cdot,t} \sim N(\vec{0}, \Sigma).$$

138 We specified the covariance matrix Σ as the diagonal decomposition $\Sigma = DMD$, where D
139 is a diagonal matrix of stock-specific standard deviations σ_s , and M is the matrix of stock
140 correlations. For simplicity, we simulated all stocks with identical pair-wise covariances, i.e.,
141 for a 3 stock complex

$$M = \begin{pmatrix} 1 & 0.5 & 0.5 \\ 0.5 & 1 & 0.5 \\ 0.5 & 0.5 & 1 \end{pmatrix},$$

142 and all stocks experienced the same magnitude of stock-specific process errors where $\sigma_s = \sigma$,
 143 implying

$$D = \begin{pmatrix} \sigma & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & \sigma \end{pmatrix}.$$

144 The operating model values of κ and σ were chosen to give a total process error variance of
 145 $\sigma^2 + \kappa^2 = 0.01$, or roughly a 10% total relative standard error (Table 1).

146 We simulated 34 years of fishery history from 1984 ($t = 1$) to 2017 ($t = 34$). Each stock
 147 was initialized in 1984 at a pre-determined depletion level $d_{s,1}$ relative to unfished biomass,
 148 i.e., $B_{s,1} = d_{s,1} \cdot B_{s,0}$. Unless otherwise stated, we set $d_{s,1} = 1$, which is varied as an
 149 experimental factor (Table 2). Because we simulated a single-species, multi-stock complex,
 150 we used the same base biological parameters $B_{s,0}$ kilo-tonnes, and r_s for all stocks s (Table
 151 1). While identical parameters may not adequately represent the true dover sole complex, it
 152 helped us focus on the effects of shrinkage in parameter estimates, rather than differences in
 153 biological parameters. This choice also simplified reporting and interpretation of the results,
 154 allowing us to focus on parameter estimates for a smaller set of representative stocks, rather
 155 than analysing every stock in the complex.

156 Fishery catch and fishery independent biomass indices were sampled from each stock each
 157 year. We simulated perfectly implemented catch $C_{s,t} = U_{s,t}B_{s,t}$, where $U_{s,t}$ was the harvest
 158 rate applied in a pulse fishing event following each year's production. We also assumed that
 159 catch was fully observed (i.e., no under-reporting). Harvest rates were simulated in three
 160 temporal phases and scaled to optimal fishing mortality as $U_{s,t} = U_t^{mult} \cdot U_{s,MSY}$, where U_t^{mult}
 161 is the piecewise linear function of t :

$$U_t^{mult} = \begin{cases} U_i + (t - 1) \cdot \frac{U_d - 0.2}{t_d - 1} & 1 \leq t \leq t_d, \\ U_d + (t - t_d) \cdot \frac{U_m - U_d}{t_m - t_d} & t_d \leq t \leq t_m, \\ U_m & t_m \leq t \leq T; \end{cases} \quad (2)$$

where U_i , U_d and U_m are the initial, development, and managed phase harvest rates, respectively, t_d is the last time step of the development phase, and t_m is the beginning of the final managed phase (Figure 3). In the base operating model, we used values $U_i = 0.2$, $U_d = 4$ and $U_m = 1$ for harvest rate multipliers, with $t_d = 5$ (1988), and $t_m = 15$ (1998) for phase timing, to simulate a high initial development phase followed by a reduction in pressure, allowing the stock to recover. This formulation was designed to create more and less informative catch histories, depending on the parameter values (Schnute and Richards 1995).

Survey indices of biomass were simulated for each stock s and survey o via the observation model

$$I_{o,s,t} = q_{o,s} B_{s,t} e^{\delta_{o,s,t}},$$

where $q_{o,s}$ is stock-specific catchability coefficient for survey o . Observation errors were simulated via the distribution

$$\delta_{o,s,t} \sim N(0, \tau_o),$$

where τ_o is the survey observation error log scale standard deviation for survey o . Within each survey, stock-specific catchabilities $q_{o,s}$ were randomly drawn from a log-normal distribution with a mean survey catchability coefficient $\bar{q}_o$ and between-stock log-standard deviation $\iota_{q,o}$ via

$$q_{o,s} \sim \log N(\bar{q}_o, \iota_{q,o}).$$

It is not always the case that catchability will be correlated closely between stocks. Indeed, we were able to model catchability as a correlated process between stocks because we used swept area biomass estimates as our stock indices. To see this, note that the general formula for catchability is $q = ca/A$, where c is gear efficiency, a is the average area fished by the gear during the survey, and A is the total area of the surveyed stock's habitat (Arreguín-Sánchez 1996). Because the geographic boundaries of stocks may differ, it will usually be the case that $A \neq A'$ between 2 distinct stocks s and s' , even if the average surveyed area a and gear efficiency c are the same. For a trawl survey, it is advantageous that the area swept

by the fishing gear is often known exactly, with $a = t \cdot v \cdot w$, where t is the standard tow duration, v is the tow velocity and w is the door-width of the trawl net. Therefore, the total of randomly sampled survey catches $C_t = qE_tB_t$ from a total effort of $E_t = n_t$ tows can be transformed into biomass estimates when scaled by the reciprocal of the proportion of area swept, e.g. $B'_t = \frac{A}{n_t a} C_t = cB_t$. Then the effect of stock area is scaled out of the index, and catchability is reduced to gear efficiency c , or the response of individual fish to the survey gear. We then assumed that this response is similar between individuals of the same species. This calculation extends to swept area biomass estimates calculated from a stratified survey, like the trawl survey used for Dover Sole.

We simulated biomass indices from two surveys operating over different periods to emulate the current dover sole complex history (Figure 2). The first ($o = 1$) represented Survey 1, which operated from 1984 to 2003 ($t = 1, \dots, 20$), with observation model parameters $\tau_1 = 0.2$ for the observation errors, and a mean survey catchability of $\bar{q}_1 = 0.5$ with a standard deviation of $\iota_{q,1} = 0.1$. For survey 2 ($o = 2$), which operated from 2003 to 2017 ($t = 20, \dots, 34$), we modeled an observation error standard deviation of $\tau_2 = 0.4$, and a mean catchability of $\bar{q}_2 = 0.6$ with a standard deviation of $\iota_{q,2} = 0.1$.

Assessment model

We estimated stock-specific biological and management parameters using multi-stock and single-stock versions of a state-space Schaefer stock assessment model. We minimized the effect of assessment model mis-specification by matching the deterministic components of the biomass dynamics in the assessment models and the operating model, Equation (1). Details of the assessment model prior distributions are not presented in this section. Instead, the equations for each multi-level prior in the hierarchical multi-stock assessment model are given in Table 3, and the details of all prior distributions are given in supplementary material S1.

Hierarchical multi-stock assessment models For the full hierarchical multi-stock model, we defined shared prior distributions on (1) conditional maximum likelihood estimates of stock-specific catchability $\hat{q}_{o,s}$ within each survey and (2) optimal harvest rate $U_{s,MSY}$, which was used as a surrogate for stock productivity (Table 3). In total, we defined 4 configurations, including a “null” multi-stock model. Each multi-stock model configuration was defined by whether each of the hierarchical priors was estimated along with the leading model parameters. When a hierarchical prior was “off”, shared priors were bypassed and the model used the fixed hyperprior mean and standard deviation instead (Table 3, Single level priors). Full details of the single and multi-level priors are in supplemental material.

Single-stock assessment model The single-stock assessment model was defined as a special case of the multi-stock null model. Prior distributions on catchability and productivity were the single level priors (Table 3, q.4 and U.4).

Optimization Assessment models applied the Laplace approximation to integrate the objective function over random effects, obtaining a marginalized likelihood (Kristensen et al. 2015). The marginalized likelihood was then maximized via the `nlminb()` function in R to produce parameter estimates and corresponding asymptotic standard errors (R Core Team 2015). We considered an assessment model converged when the optimisation algorithm reported convergence, which was characterized by gradient components of the TMB model all having magnitude less than 0.0001, and a positive definite Hessian matrix. Standard errors of derived parameters were estimated from the Hessian matrix using the delta method. The estimated process errors $\zeta_{s,t}$ were treated as random effects for all model configurations, and stock-specific catchability parameters $\log q_{os}$ were treated as random effects when the shared catchability prior was estimated.

Simulation experiments

We used an experimental design approach to investigate performance of the four hierarchical multi-stock assessment model configurations under different levels of statistical power in the simulated data. Multiple scenarios were used to determine whether (and possibly to what extent) hierarchical multi-stock assessment methods could provide better estimates of key management parameters, compared to single-stock approaches, when fitted to data with low statistical power.

Experimental factors were selected to increase and decrease the statistical power, or quality, of the simulated assessment data. The choice of factors determining high- and low-information scenarios was guided by previous studies of assessment models, as well as our own experience with production model behaviour (Hilborn 1979; Magnusson and Hilborn 2007; Cox et al. 2011). Combinations of experimental factors were chosen according to a space-filling experimental design (Table S1) (Kleijnen 2008). Space filling designs improve the efficiency of large simulation experiments by reducing the number of individual runs, while still producing acceptable estimates of factor effects.

We represented high and low statistical power scenarios by varying 5 experimental factors: (1) historical fishing intensity; (2) the number S of stocks in the complex; (3) the number L of low information stocks in the complex; (4) the initial year of stock assessment T_1 for the L low information stocks; and (5) the initial stock depletion levels $d_{s,1}$ for the L low information stocks (Table 2).

We defined 2 levels of historical fishing intensity, which modified U_i , U_d and U_m in Equation (2). Levels were chosen to produce one-way and two-way trip dynamics when the simulated biomass was initialized at unfished equilibrium in 1984. One way trips were produced by fishing at a constant rate of $U_{s,MSY}$ for the whole historical period (top row, Figure 3), while the two-way trips were produced by the base operating model settings (bottom row, Figure 3). The constant harvest rate scenarios had two significant disadvantages: first, it is impossible, in general, to estimate the optimal harvest rate without overfishing (Hilborn

and Walters 1992, Ch 1), which does not occur in these scenarios; second, when stocks were initialized at fished levels it was difficult to determine the stock size and initial biomass.

Complex sizes S were chosen to test the intuitive notion that grouping more stocks together increases the benefit of shrinkage. We tested the sensitivity of this notion to relative differences in the number of stocks via the factor L , which determined how many of the S stocks were “low information”. Low information stocks had short time series and fished initialisation at a pre-determined relative biomass level, which together reduced or removed the contrast in the biomass dynamics and lower the quality of observational data. By initializing the assessments of low information stocks when Survey 2 was initiated, and simulating Survey 2 as a shorter and noisier series of observations, we subjected those stocks to non-equilibrium starting conditions as well as poor quality survey data, a situation that is likely common for data-limited fisheries. When $L > 0$, we estimated the initial biomass B_{s,T_1} for the low information stocks in addition to unfished biomass, optimal harvest rate and catchability.

We fit the single-stock and each hierarchical multi-stock assessment model configurations to simulated data under each combination of experimental factors. The distributions used for the single-level and multi-level hyperpriors (Table 3, q.2, q.4, U.2, and U.4) were given random mean values m_q and m_U in each simulation replicate, chosen from a log-normal distribution centred at the true mean value (across stocks, and possibly surveys) with a 25% coefficient of variation. This randomisation was used to test the robustness of the assessment model to uncertainty in the prior distribution. The same initial seed value R was used across all experimental treatments so that variability in assessment error distributions was predominantly affected by the factor levels and model configurations, rather than random variation in the process and observation errors. Random variation was not completely avoidable, though, as assessment models would fail to converge for some combinations of treatment and random seed values. In these cases we restarted the optimisation with jittered initial parameter values up to 20 times, after which we moved on to a different random

seed value. The total number of replicates for each experiment and prior configuration are shown in Table S1.

Performance metrics

We measured performance of both the single-stock and multi-stock assessment models by their ability to estimate current biomass $\hat{B}_{s,2017}$, MSY level biomass $\hat{B}_{s,MSY}$, equilibrium optimal harvest rate $\hat{U}_{s,MSY}$, and relative terminal biomass $\hat{B}_{s,2017}/\hat{B}_{s,0}$. We also found catchability estimates $\hat{q}_{o,s}$ to be important in the analysis of these models, so we calculated performance metrics for catchability as well.

It is important to understand the effect of shrinkage on the bias and precision of estimates of the key parameters θ above, because such shrinkage may result in misleading harvest advice. For example, shrinkage may simultaneously increase both bias and precision for a given parameter (e.g. MSY), leading to confidence intervals that may not contain the true parameter value. Therefore, we used four performance metrics to represent these effects: (1) median relative errors (MREs); (2) ratios of median absolute relative errors (MAREs); (3) confidence interval coverage probability (IC); and (4) the predictive quantile. All metrics are defined in detail below. While MREs only indicate model bias, all other metrics are affected by both the bias and precision of the estimator, and can be better interpreted when the bias is known.

For MRE and MARE metrics, we calculated relative errors $RE(\hat{\theta}_{i,s})$ of the model estimate $\hat{\theta}_{i,s}$ for each replicate i and stock s , i.e.

$$RE(\hat{\theta}_{i,s}) = 100 \cdot \left(\frac{\theta_{i,s} - \hat{\theta}_{i,s}}{\theta_{i,s}} \right).$$

Estimator bias and precision were quantified by computing the median relative error $MRE(\theta_s) = \text{med}(RE(\hat{\theta}_{\cdot,s}))$ and median absolute relative error $MARE(\theta_s) = \text{med}(|RE(\hat{\theta}_{\cdot,s})|)$ of relative error distributions $RE(\hat{\theta}_{\cdot,s})$ over all replicates i . We chose to use MAREs because they are

independent of scale and less sensitive to outliers than root mean square errors. Values closer to zero indicate better performance for both metrics, with lower MRE values indicating lower bias, and lower MARE values indicating lower bias, higher precision, or both.

In the simulation experiments we compared assesment models via ratios of single-stock to multi-stock MARE statistics for each stock s and parameter θ , i.e.,

$$\Delta(\theta_s) = \frac{MARE_{ss}(\theta_s)}{MARE_{ms}(\theta_s)} - 1, \quad (3)$$

where ss and ms represent the MARE values for the single- and multi-stock hierarchical assessment model estimates, respectively. Using this definition, $\Delta(\theta_s) > 0$ occurred when the multi-stock assessment model had a lower MARE value, indicating that multi-stock estimates had higher precision, lower bias, or both. Estimation performance for an assessment complex as a whole was indicated by an aggregate MARE ratio $\bar{\Delta}(\theta_s)$ for each stock's parameter θ_s , i.e.,

$$\bar{\Delta}(\theta) = \frac{\sum_s MARE_{ss}(\theta_s)}{\sum_s MARE_{ms}(\theta_s)} - 1,$$

which allowed us to compare estimation performance of single and multi-stock assessment models over the whole assessment complex.

Interval coverage probability was calculated across reps i within each combination of experimental factors and model configuration. We calculated the realized interval coverage probability under an assumption of normality on the log scale, because all quantities of interest are constrained to be positive, and chose the nominal coverage probability as 50%, with a corresponding z -score of 0.67. These two choices defined our interval coverage probability metric as

$$IC_{50}(\log \theta_s) = \frac{1}{100} \sum_i I(\log \theta \in (\log \hat{\theta}_{i,s} - 0.67 \hat{se}(\log \theta)_{i,s}, \log \hat{\theta}_{i,s} + 0.67 \hat{se}(\log \theta)_{i,s})),$$

where I is the indicator function, $\log \hat{\theta}_i$ is the model estimate of $\log \theta$ in replicate i , and

$\hat{se}(\log \theta)_i$ is the model standard error of $\log \theta$ in replicate i . For a 50% interval coverage, realized rates $IC_{50\%}(\log \theta_s)$ closer to the nominal rate 0.5 are better. The confidence interval is considered conservative when realized coverage rates are above the nominal rate, which could indicate either decreased bias of the parameter estimate or high uncertainty (larger standard errors). On the other hand, the confidence interval is considered permissive when realized rates are below the nominal rate, indicating that the uncertainty may be under-represented by the parameter estimate and its standard error.

Finally, for each parameter we calculated the distribution of predictive quantiles over replicates i , defined as

$$Q(\log \theta_{i,s}) = P(\log \hat{\theta}_{i,s} < \log \theta_{i,s}) = \int_{x=-\infty}^{x=\log \theta_{i,s}} f(x \mid \log \hat{\theta}_{i,s}, \hat{se}(\log \theta)_{i,s}) dx,$$

where $f(x|m, s)$ is the normal probability density function with mean m and standard deviation s . The resulting distribution of quantiles is best interpreted graphically, and indicates how well the model is estimating parameter uncertainty. Well performing estimators will have a near-uniform distribution of Q values, because true values should be distributed randomly across the full domain of the parameter's sampling distribution. Estimators that under-represent uncertainty by produce standard errors that are too small and will, therefore, have excess density near $Q = 0$ and $Q = 1$ (i.e a U-shaped graphical distribution), indicating that true values have larger z -scores in the sampling distribution. Models that over-represent uncertainty have standard errors that are too large and will collect density near $Q = .5$ (i.e. a $\cap$ -shaped graphical distribution), indicating lower z -scores of true values in the sampling distribution.

We used an experimental design approach for simulation models to analyse the effects of experimental factors and assessment model configurations on the MARE and Δ performance metrics (Kleijnen 2008). This method attmpts to simplify the complex response surfaces via a generalized linear meta-model of teh response surface to simulation model inputs (i.e. factor

levels and assessment model prior configurations)([McCullagh 1984](#)). Meta-models are defined in the supplemental material.

Assessment for British Columbia dover sole

We fit all 8 multi-stock assessment model configurations and the single-stock assessment model to the dover sole data for the three stocks in Figure 2. We initialized all stocks in a fished state, beginning in 1984 for the HS stock, and 2003 for both QCS and WCVI stocks.

For the prior on $B_{s,MSY}$ and $B_{s,init}$, we used a prior mean value of $m_{B,s} = 20$ and $s_{B,s} = 20$, keeping the relative standard deviation at 100%. For the process error variances, we tested two hypotheses for the strength of environmental effects on population dynamics. These were implemented as choices for the β parameters of the inverse-gamma prior distributions on process error variance terms, when using $\alpha_\sigma = 3$. The first choice was to use $\beta_\sigma = 0.16$, placing the prior mode at around 0.04, favouring process errors with a larger standard deviation around $\sigma = 0.2$. The second was to use $\beta_\sigma = 0.01$, reducing the prior mode to 0.0025, favouring process errors with a small standard deviation around $\sigma = 0.05$.

For each model fit, we calculated Akaike’s information criterion, which we corrected for the sample size (number of years of survey data) for each stock (AICc) ([Burnham and Anderson 2003](#)). We then selected the group of multi-stock configurations that performed the best under both hypotheses according to their AICc values, and present estimates of optimal harvest rate $U_{s,MSY}$, terminal biomass $B_{s,T}$, optimal biomass $B_{s,MSY}$, relative biomass $B_{s,T}/B_{s,0}$, and current fishing mortality relative to the optimal harvest rate $U_{s,T}/U_{s,MSY}$, as well as standard errors for all estimates. We used the sum of single-stock AICc values to represent the complex aggregate AICc score for comparing single-stock and multi-stock model fits. While this may be a slight deviation in use of the AIC, we believe it is both useful and satisfies the restrictions of the AICc, i.e., the collection of single-stock models is fit to the same data as the multi-stock models, and the process of adding AICc values is analogous to adding single-stock model log-likelihood values within a joint likelihood.

Results

When discussing experimental results, we restrict our attention to stock $s = 1$, a low information stock if $L > 0$ in the information scenarios, and identical to the remaining stocks otherwise. We initially focus on the meta-model effects on MARE ratios $\Delta(\theta_s)$ and complex aggregate $\bar{\Delta}(\theta)$ to interpret model configuration effects, and use the remaining metrics to help interpret factor effects.

Single-stock versus multi-stock assessments of the base operating model

As expected, shrinkage effects from hierarchical multi-stock assessment models often improved precision of key management parameter relative errors from multi-stock models compared to single-stock models, when fit to data from the base operating model (Figure 4). Although this pattern extended across most model configurations and variables, the effect was most noticeable for optimal harvest rate U_{MSY} and optimal biomass B_{MSY} , and weakest for absolute B_T and relative B_T/B_0 terminal biomass. Also, the effects of hierarchical priors were most noticeable for parameters that were subject to those priors, i.e. catchability had larger increases in precision under a model configurations that estimated a shared prior on catchability (Figure 4, q_1, q_2 under the q AM configuration).

We found that estimator bias was less sensitive to hierarchical multi-stock configurations, with sometimes very subtle effects. For example, for optimal harvest rate U_{MSY} , optimal biomass B_{MSY} , and survey 1 catchability q_1 estimates were all relatively unbiased under the single-stock model, and all multi-stock model configurations had a negligible effect on the bias (Figure 4). In contrast, survey 2 catchability q_2 , and absolute and relative terminal biomass B_T and B_T/B_0 were biased under the single-stock model, so were themselves very sensitive. As with precision, the bias of catchability q_2 was most reduced by the q and q/U_{MSY} configurations, and these improvements translated directly into reductions in absolute bias

of the terminal biomass estimates B_T and B_T/B_0 .

The other performance metrics indicated that the q and q/U_{MSY} configurations performed similarly under the base operating model. For the management parameters most useful in setting harvest advice, productivity U_{MSY} and current biomass $B_T, B_T/B_0$, the q/U_{MSY} configuration either improved all metrics, or kept metrics within a tolerable level of the ideal (Figure 5), e.g. interval coverage fell for U_{MSY} , but remained within 10% of the nominal level. Similarly, predictive quantile $Q(\theta)$ distributions were slightly more uniform under the q/U_{MSY} configuration than the single-stock model, indicating an improvement in estimator precision and bias, however the difference between q and q/U_{MSY} configurations was subtle. Plots of the full set of metrics for all multi-stock model configurations and parameters under the base operating model can be found in the supplementary material (Figures S1 - S4).

Increased precision in catchability and biomass parameters under hierarchical multi-stock models was not always a benefit. Under a single simulation replicate, 95% confidence intervals of biomass estimates from joint models were generally more precise than single-stock estimates; however, increased precision occasionally created estimates that were overprecise, leaving true biomass values outside confidence intervals (Figure 6, Stock 2, q and Q/U_{MSY} models). Furthermore, hierarchical estimation appeared to falsely detect an increasing trend in biomass, where the single-stock model was more conservative (Figure 5, Stock 2), but corrected the same behaviour in the single-stock model for a different stock in the same complex (Figure 5, Stock 1).

Simulation Experiment Results

Model configuration effects

When comparing MARE values through the Δ metric, multi-stock model configurations that estimated the shared prior on survey catchability, denoted q and q/U_{MSY} , stood out as the most beneficial for parameters of the low data quality stocks (stock $s = 1$). Both of these configurations increased Δ values, or had effects that were within 1 standard error of

zero (Table 4, Stock 1 Δ values), indicating that multi-stock model configurations produced MARE values at most equal to those produced by single-stock models.

As under the base operating model, according to the Δ metric the best performing hierarchical multi-stock model for providing harvest advice was q/U_{MSY} . Closer inspection of β_q and $\beta_{U_{MSY}}$ values indicated that estimation of the mean optimal harvest rate reduced the larger benefit to catchability in both surveys $q_{1,1}$, $q_{2,1}$ and optimal biomass $B_{1,MSY}$ (Table 4, β_q and $\beta_{q,U_{MSY}}$). On the other hand, while the U_{MSY} prior had not effect on terminal biomass ($\Delta(B_T)$), the effects on relative biomass $\Delta(B_T/B_0)$ were nearly tripled over the reference level β_0 . The Δ values for optimal biomass B_{MSY} and catchability parameters were lower, but these parameters are not particularly critical for providing harvest advice.

The q and q/U_{MSY} configurations stood out at the complex level also, with higher meta-model coefficients than the U_{MSY} configuration (Table 4, Complex Aggregate $\bar{\Delta}$ Values). Under the aggregate MARE ratio $\bar{\Delta}$, it was more difficult to separate the two best models as the meta-model coefficients for both q and q/U_{MSY} were closer together, e.g. $\bar{\Delta}(B_T)$, and there was a reduction in $\bar{\Delta}(U_{MSY})$ under the q/U_{MSY} configuration. Unlike the stock-specific Δ values, the prior configuration had an effect on the $\bar{\Delta}(U_{MSY})$ response in the aggregate, where the q/U_{MSY} configuration produced the biggest reduction $\bar{\Delta}(U_{MSY})$. On the other hand, the largest increase over the null model reference level was also produced by the q/U_{MSY} configuration for the $\bar{\Delta}(B_T/B_0)$ response, indicating a tradeoff between estimates of stock status and productivity.

The U_{MSY} configuration tended to perform the worst according to the Δ metric. We expected to see a benefit to productivity parameter estimates but we were surprised to find there was no benefit to a low data quality stock. Moreover, meta-model coefficients for Δ and $\bar{\Delta}$ response variables were consistently smaller than the other configurations, and often negative or insignificant.

Factor effects

As expected, the effects of shrinkage were most beneficial under low-information scenarios, according to the Δ metrics. When the biomass was initialized in a fished state, Δ and $\overline{\Delta}$ values increased (Table 4, $\beta_{ds,1} < 0$). Similarly, there were significant increases in Δ and $\overline{\Delta}$ values for all parameters when the assessments were initialized at the beginning of survey 2 (Table 4, $\beta_{T_1} > 0$). These improvements under low information conditions are largely driven by a stabilising effect of shrinkage. That is, single-stock models produced relatively larger MARE values as data data quality was reduced. Under the same conditions, the hierarchical multi-stock models were restricted from increasing MARE values as fast by shrinkage (Table 4).

We found that the q and q/U_{MSY} configurations were sensitive to data quality and the choice of performance measure. For example, under a 1-way trip fishing history with 4 identical stocks (Figure 7), the q configuration eliminated bias in U_{MSY} and improved interval coverage from 62% to 56%, correcting an under-precise estimator. In contrast, the q/U_{MSY} configuration was over-precise, indicated by an interval coverage of 33% and the quantile distribution becoming slightly U-shaped, and also increased bias in U_{MSY} estimates (Figure 7, U_{MSY}).

On the other hand, the q/U_{MSY} configuration appeared to perform better under a 2-way trip fishing history, a short time series, and fished initialisation. The q/U_{MSY} configuration reduced bias for relative biomass B_t/B_0 and almost eliminated bias for U_{MSY} (Figure 8, U_{MSY}). Interval coverage also improved under the q/U_{MSY} configuration for terminal biomass estimates B_T and B_T/B_0 , coming closer to the nominal rate of 50%. Although the U_{MSY} interval coverage fell to 36% under the q/U_{MSY} configuration, indicating an over-precise estimator, we viewed this as favourable compared to the q configuration, where U_{MSY} was under-precise by a similar amount, yet remained positively biased.

The effect of complex size S and the number of low information stocks L interacted in unexpected ways. According to the selected meta-model, the size of the complex S and the

number of low information stocks L appeared to have little effect on response values. Indeed, all β_S and β_L effects on Δ and $\bar{\Delta}$ values were at most 0.09 in magnitude, if they were included at all. These weak effects indicated that the linear meta-model is probably too simple for these factors (Figure 9). Increasing the number of low-information stocks L was always an improvement for Δ values when moving from $L = 0$ to $L = 1$. This was expected given that the Δ values were calculated for stock $s = 1$ (a data poor stock if $L > 0$), and we expected that multi-stock models and single-stock models would have similar estimates when fit to complexes of data-rich stocks. Beyond $L = 1$ any improvements in MARE values were dependent on the size of the complex. Generally, it appeared that keeping the number of low information stocks under half of the complex size, i.e. $L < S/2$, preserved the most benefit in terms of precision, though this pattern reversed for $L = 3$ and $S = 4$. Complex aggregate $\bar{\Delta}$ values were comparatively flatter in response to the levels of L . We didn't produce response surfaces for other factor combinations as these factors all had 2 levels each, meaning that a linear model should capture the average behaviour.

Assessments of British Columbia dover sole

Multi-stock models defined by shared catchability q and shared catchability and optimal harvest rate configurations q/U_{MSY} performed best for the British Columbia dover sole complex based on AICc values. These same configurations also performed best in the simulation experiments. The U_{MSY} configuration and the null model both had AICc scores more than 500 points higher than the best performing multi-stock configuration. The selected multi-stock models gave AICc scores between 100 and 200 units below the total single-stock model scores under both hypotheses (Table 5, AICc), indicating that the increase in estimated parameters was justified. All models had lower AICc values under the assumption of low process error variance.

Hierarchical multi-stock models reduced parameter uncertainties when compared to single-stock models. Multi-stock models with shared priors produced lower coefficients of variation,

defined as $CV = \sqrt{e^{se^2} - 1}$, for estimates of optimal biomass and productivity parameters, reducing coefficients of variation below 100% in some cases (single-stock vs multi-stock models in Table 4). Similar reductions in uncertainty are visible in reconstructions of stock biomass time series (Figure 10).

Assessments of the dover sole complex were qualitatively similar between model configurations and hypotheses. The major differences between assessment model configurations were the level of uncertainty in parameter estimates, and the scale of each individual stock's biomass, but the trends over time were the same (Figure 10). The Hecate Strait (HS) stock showed increasing biomass since 1984, with more or less process variation depending on the configuration and variance hypothesis (Figure S5). The Queen Charlotte Sound stock showed an initial depletion with increased landings between 2003 and 2006, followed by some growth that has continued until present day. Finally, the West Coast of Vancouver Island (WCVI) stock showed a flat biomass trend following initial depletion from 2003 to 2006. The flat trend in the WCVI stock may indicate that fishing was balancing annual production.

We found that the multi-stock assessment model configuration q/U_{MSY} generally estimated all stocks as smaller and more productive than other assessments (Table 5). This was most noticeable for the QCS stock biomass estimates by multi-stock models, where the single-stock model considered the optimal biomass to be close to 18 kt, with a terminal relative biomass between 7% and 13%, in contrast to the selected multi-stock configurations, where optimal biomass was between 3 kt and 6 kt, with a current relative biomass between 95% and 110%. Under the single-stock model configuration, the biomass scales corresponded to expected catchability values of $q_{2,HS} = 0.10$, $q_{2,QCS} = 0.74$ and $q_{2,WCVI} = 0.16$. We considered this distribution of catchability values between stocks of the same species unlikely, given that the biomass indices are relative biomass values and catchability corresponded to trawl efficiency. It was more likely that the single-stock assessment reduced the biomass parameter estimates for the QCS stock because of the fished initialisation in 2003. Starting in this state removed any depletion signal from the earlier catch history, and allowing the

model to explain the stock indices catch with a smaller biomass.

No selected multi-stock model indicated that dover sole stocks were overfished or experiencing overfishing, however, the uncertainty in relative terminal biomass and harvest rate was often very high. That is, current relative biomass estimates were always at least 60% of unfished, but their coefficients of variation were in some cases above 50% of the mean estimate (Table 5). Similarly, although relative harvest rate estimates were all at most 70% of the optimal harvest rate (Table 5), their coefficients of variation were at least 65%, and sometimes greater than 100%, of the mean estimate for each stock under some model configurations, most often under the high variance assumption.

The q/U_{MSY} hierarchical multi-stock model configuration had the best fit to the data, which is not surprising given that the dover sole complex closely matches the scenario shown in Figure 8, with a fished initialisation and 2 stocks having short time-series of observations. Under those simulation experiments, the q/U_{MSY} configuration was considered over-precise, but essentially unbiased, for U_{MSY} estimates. In contrast, for assessments of dover sole data with low process error variance, the precision seems be lower under the q/U_{MSY} configuration, indicated by larger coefficients of variation (Table 5).

Discussion

Our simulation results indicate that, as expected, shrinkage effects in hierarchical multi-stock assessment models are most beneficial when some data sets have low statistical power. Furthermore, both configurations that estimated a shared catchability prior performed best for estimating key management parameters. On the other hand, we found that shrinkage does not always improve stock assessment performance relative to a single-stock approach. In particular, the benefits of joint estimation depend on several factors, including the information content of the data, the choices for hierarchical model priors, and the particular management parameters of interest.

Model configurations that shared prior distributions on survey catchability (q and q/U_{MSY}) stood out as the best options for improving parameter estimates for stocks with low data quality. This result may occur because catchability is a linear parameter within the assessment, while optimal harvest rate parameters are embedded within non-linear population dynamics. Although this hypothesis does not explain how different configurations increase or reduce bias and precision, it may provide a template to guide expectations and generate hypotheses when testing other hierarchical model behaviour.

We found that simply adding a joint likelihood can have positive effects, which was surprising because there should be no mathematical difference between optimising a set of single-stock models independently vs binding them in a joint model by simply adding their negative log likelihoods together. This result may indicate a stabilising effect from the joint likelihood, where simply including data-rich species without shared priors improves the numerical performance of minimisation algorithm.

There was mixed evidence that increasing the size of the assessment complex produced better results under hierarchical multi-stock models. For instance, in the lower information scenarios, the effect of the complex size depended on the number of low-information stocks present in the system. The most benefit for the first stock $s = 1$ was realized when moving from no low information stocks ($L = 0$) to one low information stock ($L = 1$). This is counter-intuitive, as decreasing information should reduce precision, but represents the stability induced by the shrinkage from the multi-stock models. Looking at response surfaces averaged over all factor levels and configurations, we found that complexes of size $S = 7$ provided the most stable benefit (in terms of MARE values) for different numbers of low information stocks L ; however, we weren't testing for an optimal size, which would require a new design with a finer resolution on L and S factors.

Some of our results may be caused by a discrepancy between the underlying assumption of normality for parameter distributions used in the Laplace approximation to the integrated likelihood and the true parameter distribution (Kristensen et al. 2015). Despite the inte-

grated likelihood, the approximation by a normal distribution means that there is potential for bias caused by disagreement between the modes of the assumed normal distribution and true parameter distribution (Stewart et al. 2013).

Although we investigated a single-species, multi-stock complex, where stocks represented biologically identical management units within the dover sole fishery, the hierarchical multi-stock approach could be extended to a multi-species approach by simulating stocks with different biological parameters $B_{s,0}$ and r_s . We suspect that a differences in unfished biomass $B_{s,0}$ would not have a strong effect on overall performance. In a Schaefer model context, the unfished biomass parameter determines the absolute scale at which the dynamics operate, but has little effect on the dynamics themselves. Density dependence in annual production is driven by this parameter, but that effect is independent of absolute biomass and relies, instead, on the relative biomass B_t/B_0 . In contrast, differences among intrinsic growth rates may improve estimates in assessment models that estimate shared productivity priors. More productive stocks would grow faster when fishing pressure is reduced, reducing uncertainty in productivity estimates for those stocks. Stocks with more precise estimates may then have a dominating effect on the hierarchical prior, improving hierarchical assessments but potentially biasing estimates of weaker stock productivities (Raudenbush and Bryk 2002).

Multi-species extensions to the framework we’ve presented here may also provide deeper insights. For example, introducing age-structured population dynamics (Fournier et al. 1998), or a delay-difference formulation (Schnute 1985), would differentiate multiple species further than a simple Schaefer model by allowing for different maturation delays, growth rates, and recruitment dynamics to affect stock production. If biological data were unavailable for informing life-history parameter estimates under more realistic population dynamics, meta-analyses of Beverton-Holt life history invariants within family groups could provide informative prior distributions (Nadon and Ault 2016). Indeed, recent meta-analyses have shown that publically available data-bases of life history parameters can be useful for this type of application (Thorson et al. 2014). Similar meta-analyses of the same data-bases,

comparing species that are evolutionarily related, improves the utility of life history invariants by estimating different ratios within taxa, improving their utility as informative priors and potentially providing inverse-gamma priors on hierarchical variance terms in the form of evolutionary covariance estimates (Thorson et al. 2017).

We made several simplifying assumptions about the population dynamics for simplicity in design and interpretation. In addition to assuming that biological parameters are the same for stocks within the complex, we assumed fishing pressure was identical among stocks, and the magnitude of species-specific effects was identical. The choice of identical biology removed a “stock-effect” on management parameter estimates, as discussed above for productivity. With different biological parameters, the ability to identify hierarchical estimator effects may be reduced due to confounding with stock effects. Next, subjecting stocks to identical fishing pressure simplified the generation of assessment data. Simplifying the simulations in this way may have increased the correlation between stocks, improving performance of the hierarchical multi-stock estimators relative to more realistic situations. For example, it would be more realistic to link fishing mortality to fishing effort through a stock-specific fishery catchability.

We also made simplifying assumptions when defining the assessment model treatment of stock-specific effect $\zeta_{s,t}$. These assumptions were identical standard deviations, which matched the simulated dynamics, zero correlation in $\zeta_{s,t}$ process errors, which did not match the simulated dynamics, and we avoided estimating the shared year effect $\bar{\epsilon}_t$, despite simulating these effects. The reason for the second assumption was for stability in simulation trials, as estimating the correlation often produced nonsensical results. It may be possible to address this by applying an inverse Wishart prior for the full estimated covariance matrix, but we did not consider this within the scope of this research. We avoided estimating the shared year effect as this was removed from the experimental design after it was clear that we would be unable to reliably estimate it, and there was no benefit to partitioning the variance across an extra process error term. Adding another data stream, such as an environmental

index (Malick et al. 2015), or forcing the year effects to resemble a periodic or trend-zero behaviour (Walters 1986), may improve these estimates in other studies.

We did not conduct sensitivity analyses of the hyperpriors. Intuitively, we expect that more precise inverse-gamma hyperpriors on estimated variance parameters would increase the shrinkage effect, and thereby clustering stock-specific estimates closer to a biased mean value. Instead of focusing on the behaviour induced by hyperprior settings, we chose instead to focus on the behaviour induced by defining the shared priors, and left the hyperpriors on prior means sufficiently vague to emulate the true prior knowledge about the dover sole complex, and on prior variances sufficiently informative to encourage a shrinkage effect.

Fitting the hierarchical multi-stock surplus production models assessment to dover sole data showed that shrinkage effects carried over to a real system. Shrinkage effects reduced uncertainty when data had low statistical power, and provided more realistic estimates of catchability parameters than single-stock models, especially for the Queen Charlotte Sound stock. While the resulting estimates were sometimes quite uncertain, and a full assessment would require more scrutiny or a different model structure than we have provided here, our results indicate that all three dover sole stocks are likely in a healthy state given recent rates of exploitation.

Our results confirm that hierarchical multi-stock production models are a feasible data-limited approach to stock assessment in multi-stock fisheries. Under low statistical power conditions, hierarchical multi-stock assessment modeling is preferable to data-pooling approaches for at least two reasons. First, hierarchical multi-stock models are able to produce stock-specific estimates that allow management decisions to be made at a higher spatial resolution and based on data rather than strong *a priori* assumptions or management parameter values averaged over stocks. Despite the potential for bias under low-power conditions, stock-specific estimates of key management parameters can provide meaningful and important feedback in the fishery management system. Second, using a hierarchical multi-stock method ensures that an assessment framework is readily available for more and better data,

making it much easier to update model estimates later when more data is available. Moreover, the type of additional data to be collected could be prioritized by examining the standard errors for observation model components of the hierarchical multi-stock assessment models, where higher uncertainty may indicate a better return on investments in improved monitoring.

The feasibility of hierarchical multi-stock surplus production models relies on catch and effort data being available, but we consider hierarchical multi-stock production models as an important bridge between catch-only methods and more data-intensive methods. For instance, some catch only methods require restrictive *a priori* assumptions, such as an estimate of relative biomass as a model input (MacCall 2009; Dick and MacCall 2011). More recently, a multi-species assessment method was derived that removes the need for relative biomass estimates, but requires restrictive assumptions about fishery-dependent catchability and that all species are initially in an unfished state (Carruthers 2018). Our approach avoids all of these assumptions. For instance, (i) joint model estimates of relative biomass were stable in practice, and in simulations despite absence of a current relative biomass estimate (or assumption); (ii) hierarchical multi-stock models have better precision when initialized in fished states; and (iii) fishery catchability assumptions are not required. Thus, while the data needs are higher for our approach, the potential applications are broader in scope.

On the other hand, hierarchical multi-stock models should be scrutinized closely via standard assessment performance measures (e.g., retrospective analysis) before application to real management systems. In particular, we found that shrinkage can have unexpected non-linear side-effects. Closed-loop simulations would be needed to determine the long-term implications of these types of errors on multi-stock harvest management systems (Punt et al. 2016).

Acknowledgements

Our funding for this research was provided by a Mitacs Cluster Grant to S. P. Cox in collaboration with Wild Canadian Sablefish, the Pacific Halibut Management Association and the Canadian Groundfish Research and Conservation Society. We specifically thank A. R. Kronlund and M. Surry at the Fisheries and Oceans Pacific Biological Station for fulfilling data requests and helpful comments on earlier versions of the manuscript. Further support to S.P.C. and S.D.N.J. were provided by an NSERC Discovery Grant to S. P. Cox. We'd also like to thank the associate editor and one anonymous reviewer for helpful comments during the peer review of this manuscript.

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Table 1: Operating model parameters and their values

Description	Symbol	Value
Unfished Biomass	$B_{s,o}$	40kt
Intrinsic Rate of Growth	r_s	0.16
Shared Process Error SD	κ	0.071
Stock-specific Process Error SD	σ_s	0.071
Simulation Historical Period	$(T_{init}, \dots, T)$	(1984, ..., 2016)

Table 2: Experimental factors and their levels

Description	Levels	Notes
Fishing History	1-way, 2-way trips	Low/High contrast in biomass
Complex Size, S	4,7,10	
Low data quality stocks, L	0,1,2,3	
Initial Assessment Year 1984, 2003	Short or long series of observations ($t = 1$ or $t = 20$ of $T = 34$ years)	
Initial Relative Depletion	0.4, 0.7, 1.0	Fished or unfished initialisation

Table 3: Multi- and single level priors used in the assessment model.

No.	Distribution
Survey Catchability	
<i>Multi-level prior</i>	
q.1	$\hat{q}_{o,s} \sim \log N(\log \hat{q}_o, \hat{t}_o)$
q.2	$\hat{q}_o \sim N(m_q, s_q)$
q.3	$\hat{t}_o^2 \sim IG(\alpha_q, \beta_q)$
<i>Single level prior</i>	
q.4	$\hat{q}_{o,s} \sim N(m_q, s_q)$
Optimal Harvest Rate	
<i>Multi-level prior</i>	
U.1	$\hat{U}_{s,MSY} \sim \log N(\log \hat{U}_{MSY}, \hat{\sigma}_U)$
U.2	$\hat{U}_{MSY} \sim N(m_U, s_U)$
U.3	$\hat{\sigma}_U^2 \sim IG(\alpha_U, \beta_U)$
<i>Single level prior</i>	
U.4	$\hat{U}_{s,MSY} \sim N(m_U, s_U)$

Table 4: Meta-model coefficients for multi-stock assessment model prior configurations (columns 3-5) and experimental factors (cols 6-10). Response variables are $\Delta(\theta_s) = \frac{MARE_{MS}(\theta_s)}{MARE_{SS}(\theta_s)} - 1$ values for stock $s = 1$ (rows 1-6), complex aggregate $\bar{\Delta}(\theta) = \frac{\sum_s MARE_{MS}(\theta_s)}{\sum_s MARE_{SS}(\theta_s)} - 1$ values (rows 7-12), single stock assessment MARE values for stock 1 (rows 13-18), and multi-stock model MARE values for stock 1 (rows 19 - 24). The intercept (col 2) is the average value of the response across all factors, and represents the null model configuration in rows 1-12 and 19-24. Coefficients of multi-stock model prior configurations independently give the average contribution of that configuration to the response value, while coefficients for experimental factors are calculated based on rescaling factors to the interval $[-1, 1]$. This means the contribution of each factor to the response is equal to its coefficient at the maximum factor value, and the negative value of its coefficient at the minimum factor value. Response values are found by summing across the rows, *taking only one prior configuration coefficient*, and scaling factor coefficients as necessary.

Response	Ref Level	Prior Configuration			Experimental Factor					
		β_0	β_q	$\beta_{U_{MSY}}$	$\beta_{q/U_{MSY}}$	Init. Dep	Init. Assessment	Low Data Stocks	Complex Size	Fishing History
						$\beta_{d_{1,1}}$	β_{T_1}	β_L	β_S	β_U
Low Data Quality Stock ($s = 1$) Δ Values										
$\Delta(U_{1,MSY})$	0.60 (0.07)	0.25 (0.09)	0.04 (0.09)	0.09 (0.09)	-0.14 (0.04)	0.35 (0.04)	-	-	-	
$\Delta(B_{1,T})$	-0.01 (0.04)	0.28 (0.05)	-0.02 (0.05)	0.28 (0.05)	-0.04 (0.02)	0.08 (0.02)	-	-	0.11 (0.02)	
$\Delta(B_{1,MSY})$	0.16 (0.03)	0.10 (0.04)	-0.07 (0.04)	0.02 (0.04)	-0.06 (0.02)	0.11 (0.02)	0.06 (0.02)	-	-0.02 (0.01)	
$\Delta(B_{1,T}/B_{1,0})$	0.32 (0.07)	0.29 (0.10)	0.13 (0.10)	0.63 (0.10)	-0.09 (0.04)	0.30 (0.04)	-	0.09 (0.04)	0.14 (0.03)	
$\Delta(q_{1,1})$	0.06 (0.05)	0.46 (0.07)	-0.01 (0.07)	0.27 (0.07)	-	0.15 (0.03)	-	-	0.06 (0.03)	
$\Delta(q_{2,1})$	-0.02 (0.02)	0.23 (0.03)	-0.05 (0.03)	0.10 (0.03)	-	-	0.03 (0.02)	-0.04 (0.01)	0.08 (0.01)	
Complex Aggregate $\bar{\Delta}$ Values										
$\bar{\Delta}(U_{MSY})$	0.47 (0.04)	0.13 (0.04)	-0.07 (0.04)	-0.07 (0.04)	-0.10 (0.03)	0.21 (0.03)	0.04 (0.03)	-	-0.03 (0.02)	
$\bar{\Delta}(B_T)$	0.04 (0.02)	0.22 (0.02)	-0.03 (0.02)	0.21 (0.02)	-0.05 (0.01)	0.11 (0.01)	-0.03 (0.01)	0.02 (0.01)	0.07 (0.01)	
$\bar{\Delta}(B_{MSY})$	0.11 (0.02)	0.11 (0.02)	-0.05 (0.02)	0.01 (0.02)	-0.07 (0.01)	0.09 (0.02)	-	-	0.03 (0.01)	
$\bar{\Delta}(B_T/B_0)$	0.31 (0.04)	0.25 (0.04)	0.03 (0.04)	0.39 (0.04)	-0.08 (0.02)	0.24 (0.03)	-	-	0.06 (0.01)	
$\bar{\Delta}(q_1)$	0.08 (0.03)	0.31 (0.03)	-0.02 (0.03)	0.21 (0.03)	-0.05 (0.02)	0.15 (0.02)	-	-	0.08 (0.01)	
$\bar{\Delta}(q_2)$	-0.06 (0.02)	0.26 (0.02)	-0.04 (0.02)	0.15 (0.02)	-0.03 (0.01)	-	-	-0.02 (0.01)	0.07 (0.01)	
Single-Stock Assessment MARE values										
$U_{1,MSY}$	40.52 (1.22)	-	-	-	-6.64 (1.49)	4.44 (1.21)	3.90 (1.66)	-	-9.00 (1.08)	
$B_{1,T}$	29.01 (0.56)	-	-	-	-0.96 (0.64)	2.62 (0.54)	-	1.01 (0.62)	2.65 (0.51)	
$B_{1,MSY}$	26.61 (0.49)	-	-	-	-5.56 (0.60)	3.67 (0.49)	3.11 (0.67)	-0.77 (0.54)	-	
$B_{1,T}/B_{1,0}$	56.13 (1.97)	-	-	-	-11.68 (2.28)	17.71 (1.93)	-	-	14.34 (1.81)	
$q_{1,1}$	19.58 (0.44)	-	-	-	-	3.46 (0.44)	-	-	-	
$q_{2,1}$	17.97 (0.41)	-	-	-	-	0.59 (0.41)	-	-0.94 (0.49)	-1.00 (0.40)	
Multi-Stock Assessment MARE values										
U_{MSY}	24.96 (0.87)	-3.54 (1.20)	0.55 (1.20)	-0.13 (1.20)	-1.70 (0.59)	-0.88 (0.47)	1.13 (0.65)	-0.78 (0.52)	-5.14 (0.42)	
B_T	29.10 (0.76)	-6.22 (1.06)	0.67 (1.06)	-5.80 (1.06)	-	0.64 (0.39)	-	0.76 (0.46)	-	
B_{MSY}	22.85 (0.78)	-1.85 (1.06)	1.28 (1.06)	-0.32 (1.06)	-4.23 (0.52)	1.28 (0.42)	1.90 (0.58)	-	-	
B_T/B_0	40.65 (1.87)	-8.77 (2.56)	-5.02 (2.56)	-13.88 (2.56)	-5.47 (1.26)	4.24 (1.02)	2.49 (1.40)	-1.67 (1.12)	6.22 (0.91)	
q_1	18.51 (0.75)	-5.39 (1.04)	-0.06 (1.04)	-3.33 (1.04)	0.69 (0.46)	1.64 (0.39)	-	-	-1.37 (0.37)	
q_1	18.51 (0.81)	-3.73 (1.15)	1.24 (1.15)	-1.54 (1.15)	-	-	-	-	-2.58 (0.41)	

Table 5: Selected management parameter mean estimates, their coefficients of variation in parentheses, and corrected Akaiques Information Criterion (AICc) values for selected stock assessments applied to the real dover sole data under the High and Low process error variance hypotheses. Model labels for multi-stock models indicate the shared priors used in the fitting process. Total AICc values for the Single-Stock model are given for direct comparison with the multi-stock models.

High Process Error Variance					Low Process Error Variance				
Model Config	HS	QCS	WCVI	Total	Model Config	HS	QCS	WCVI	Total
U_{MSY}									
Single-Stock	0.147 (0.69)	0.066 (1.14)	0.122 (0.94)	-	Single-Stock	0.113 (0.77)	0.100 (0.71)	0.136 (0.84)	-
q	0.127 (0.64)	0.092 (0.88)	0.095 (0.90)	-	q	0.115 (0.63)	0.097 (0.83)	0.104 (0.83)	-
q/U_{MSY}	0.205 (0.64)	0.191 (0.73)	0.214 (0.78)	-	q/U_{MSY}	0.156 (0.76)	0.151 (0.74)	0.170 (0.86)	-
B_T									
Single-Stock	33.189 (1.04)	4.841 (1.27)	11.487 (0.89)	-	Single-Stock	29.641 (1.13)	2.868 (0.66)	10.956 (0.83)	-
q	27.112 (0.82)	13.843 (0.85)	13.616 (0.74)	-	q	25.498 (0.79)	9.873 (0.87)	11.618 (0.77)	-
q/U_{MSY}	21.067 (0.91)	11.246 (0.93)	11.685 (0.83)	-	q/U_{MSY}	18.124 (0.96)	7.553 (1.05)	9.457 (0.88)	-
B_T/B_0									
Single-Stock	0.968 (0.67)	0.131 (1.97)	0.718 (0.80)	-	Single-Stock	0.874 (0.48)	0.077 (1.53)	0.700 (0.59)	-
q	0.917 (0.62)	1.091 (0.73)	0.702 (0.92)	-	q	0.842 (0.47)	0.950 (0.47)	0.631 (0.70)	-
q/U_{MSY}	0.932 (0.57)	1.071 (0.56)	0.830 (0.52)	-	q/U_{MSY}	0.878 (0.41)	0.967 (0.41)	0.708 (0.54)	-
U_T/U_{MSY}									
Single-Stock	0.081 (1.03)	0.597 (1.12)	0.520 (1.11)	-	Single-Stock	0.117 (0.83)	0.669 (0.65)	0.488 (0.96)	-
q	0.114 (0.85)	0.151 (1.07)	0.560 (1.04)	-	q	0.134 (0.67)	0.199 (1.03)	0.602 (0.97)	-
q/U_{MSY}	0.091 (0.87)	0.089 (1.00)	0.291 (0.95)	-	q/U_{MSY}	0.139 (0.66)	0.168 (1.01)	0.453 (0.88)	-
B_{MSY}									
Single-Stock	17.143 (0.90)	18.415 (1.53)	8.004 (0.88)	-	Single-Stock	16.951 (1.11)	18.672 (1.48)	7.830 (0.72)	-
q	14.790 (0.73)	6.343 (0.91)	9.693 (0.95)	-	q	15.142 (0.80)	5.196 (0.81)	9.210 (0.72)	-
q/U_{MSY}	11.306 (0.83)	5.250 (0.86)	7.043 (0.75)	-	q/U_{MSY}	10.323 (0.94)	3.904 (0.97)	6.680 (0.78)	-
$AICc$									
Single-Stock	-102.06	-22.487	-23.655	-148.202	Single-Stock	-163.261	-54.035	-56.802	-274.098
q				-169.838	q				-343.312
q/U_{MSY}				-252.292	q/U_{MSY}				-417.676

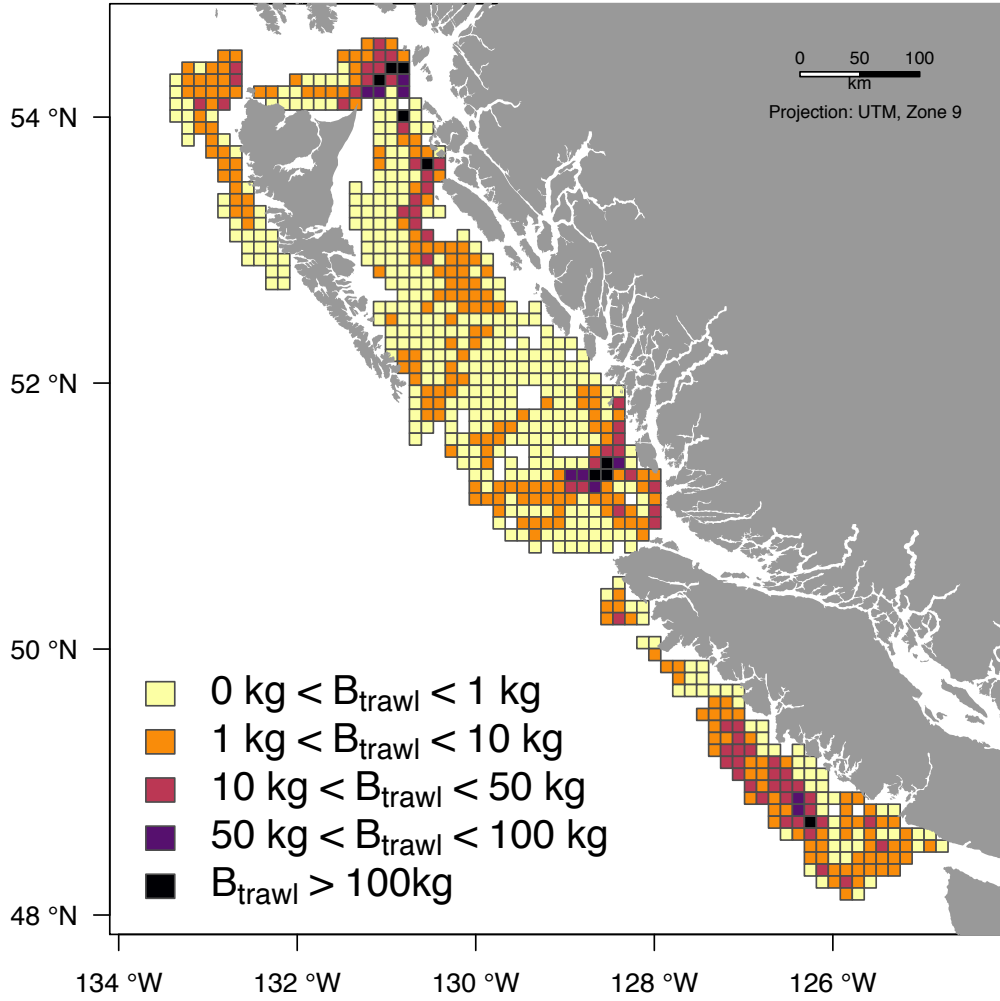


Figure 1: Minimum trawlable biomass B_{trawl} estimates for Dover Sole on the BC coast, aggregated to a 10km square grid. Estimates are produced by scaling average trawl survey (kg/m^2) density values in each grid cell by the cell's area in m^2 . Locations that do not show a coloured grid cell do not have any survey blocks from which to calculate relative biomass. Survey density data is taken from the GFBio data base maintained at the Pacific Biological Station of Fisheries and Oceans, Canada. The full colour figure is available in the online version of the article.

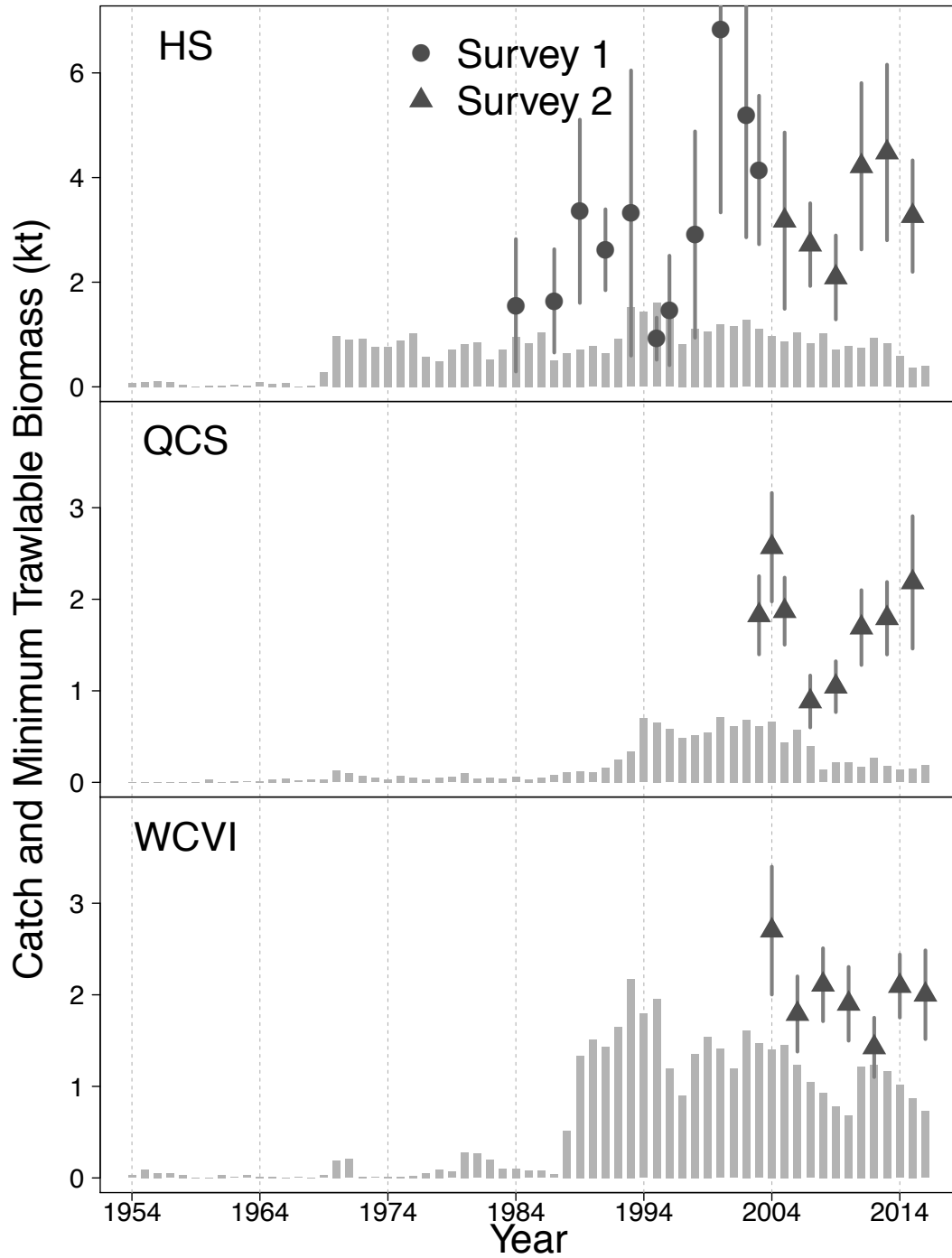
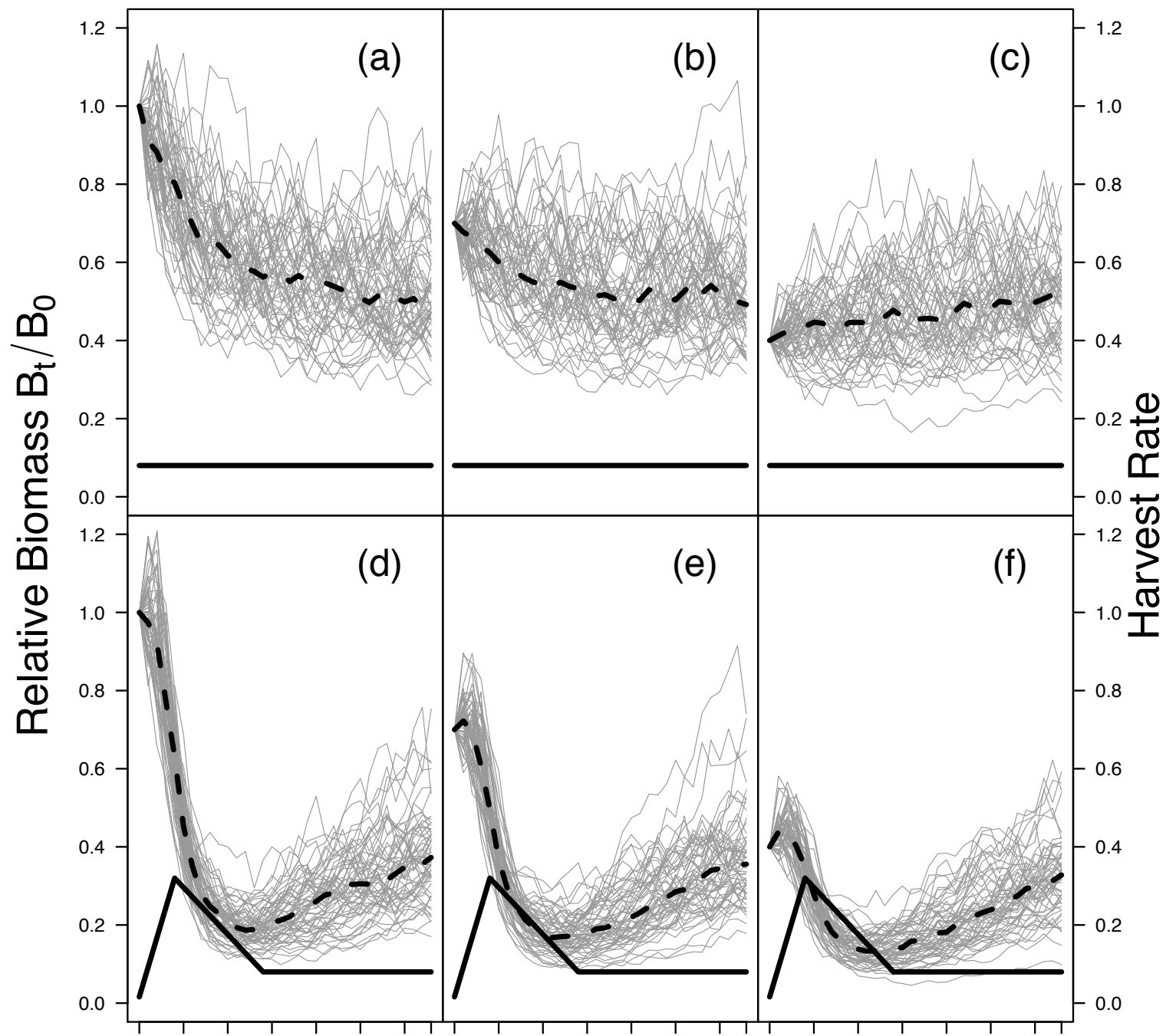


Figure 2: Time series of coastwide catch since 1954 (vertical bars) and relative biomass since 1984 (data points) for the three Dover Sole stocks: Haida Gwaii (HG), Queen Charlotte Sound (QCS) and West Coast of Vancouver Island (WCVI). The catch data are taken from the GFCatch, PacHarvTrawl and GFFOS data bases and trawl survey data were obtained from the GFBIO data base. All data bases are maintained at the Pacific Biological Station of Fisheries and Oceans, Canada.



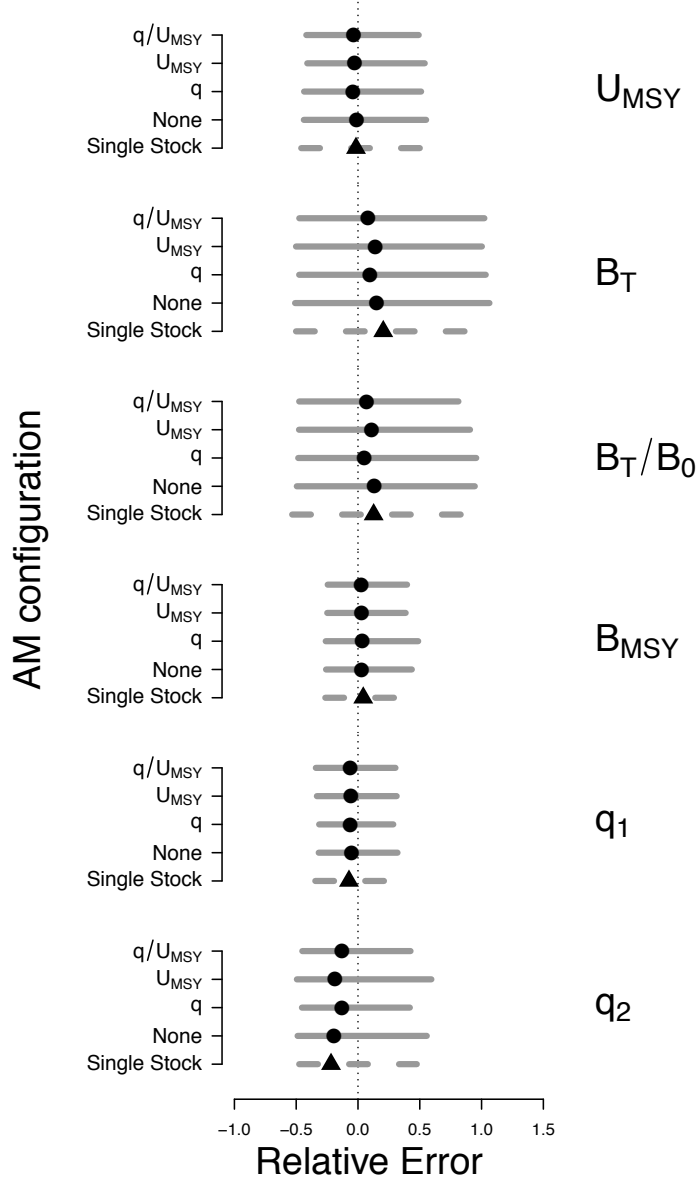


Figure 4: Relative error distributions for stock $s = 1$ leading and derived parameters estimated by the single stock (dashed lines and triangular points) and 4 multi-stock assessment models (solid lines and circular points) fit to data from the base operating model. Points indicate median relative errors and the grey lines the central 95% of the relative error distribution. From the top, parameters are optimal exploitation rate (U_{MSY}), terminal biomass (B_T), optimal equilibrium biomass (B_{MSY}), terminal biomass relative to unfished (B_T/B_0), and catchability from surveys 1 (q_1) and 2 (q_2). Assessment model (AM) configurations indicate the single stock model, or the parameters that had hierarchical prior distribution hyperparameters estimated in the multi-stock assessment model (e.g, q/U_{MSY} indicates that shared priors on both catchability and productivity were estimated).

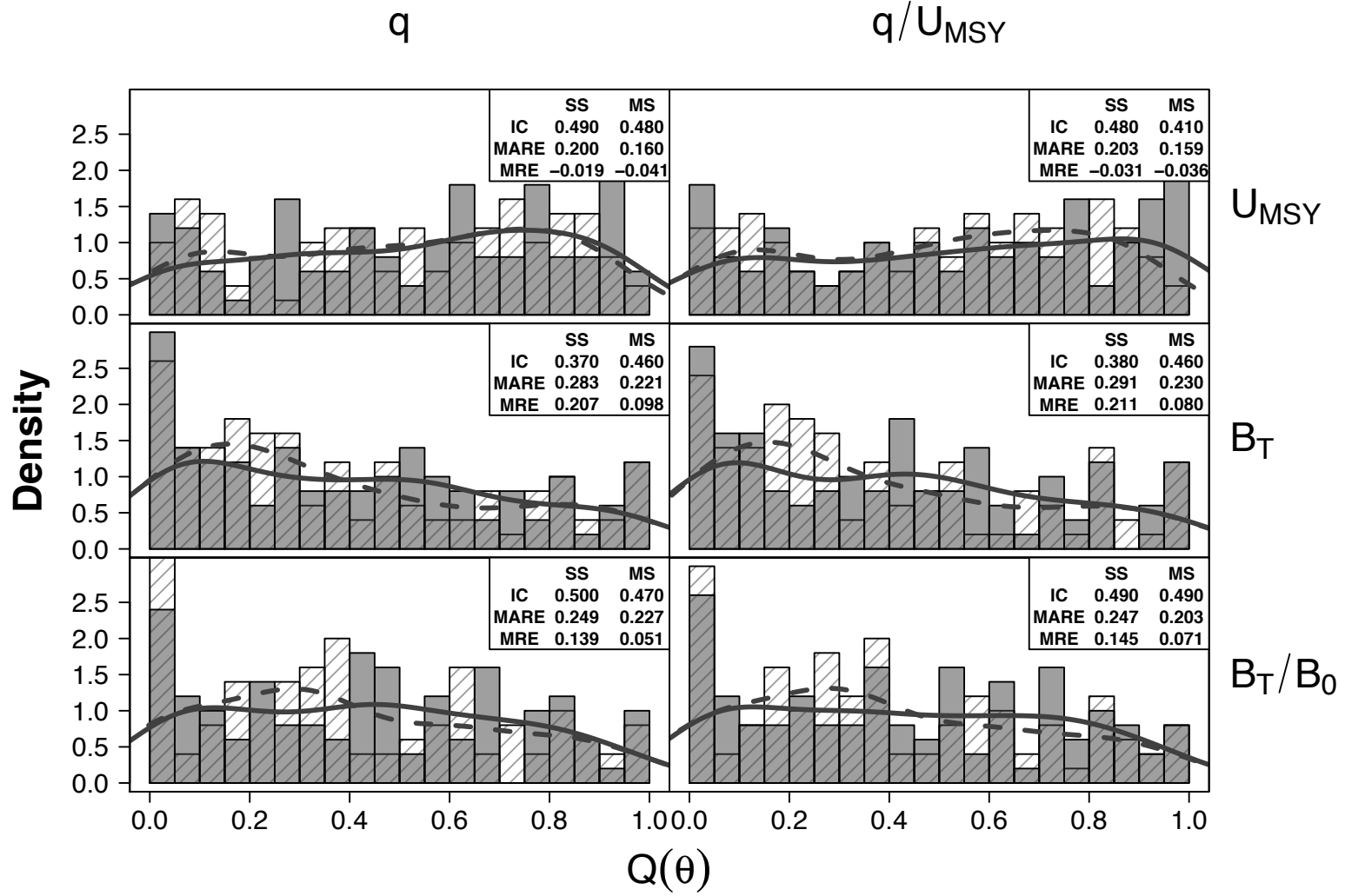


Figure 5: Density of predictive quantiles $Q(\theta)$ for estimates of key management parameters (rows) from single stock and q and q/U_{MSY} hierarchical multi-stock model configuration under the base operating model. Bars show probability density of Q distributions, with lines showing the kernel smoothed density for easier comparison between single stock (crosshatched bars and broken line) and multi-stock (dark grey bars and solid line). Top right hand corners of each panel show interval coverage (IC), median absolute relative error (MARE), and median relative error (MRE) for single stock (SS) and multi-stock models (MS).

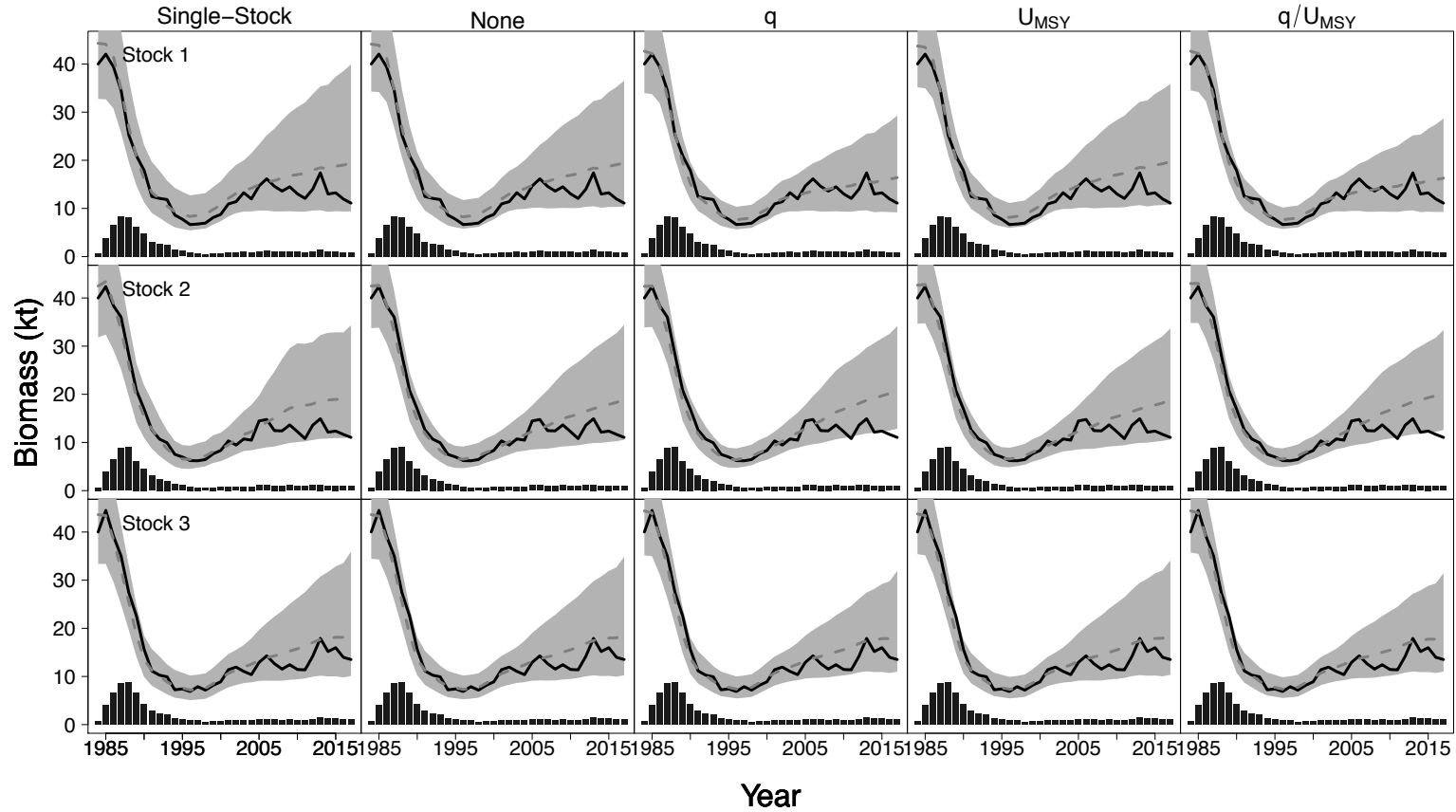


Figure 6: Time series of biomass and catch for a 3 stock complex, taken from a single simulation replicate using the base operating model. Thick unbroken lines indicate the simulated biomass values, while black vertical bars indicate the simulated catch. Assessment model estimated biomass is shown by dashed grey lines and 95% confidence intervals by shaded regions. Single-stock estimates are in the first column and the remaining columns show the four multi-stock model configurations, with titles corresponding to which shared priors are estimated. The 95% confidence intervals are calculated from the Hessian matrix for leading model parameters using the Δ -method by TMB's `ADREPORT()` function.

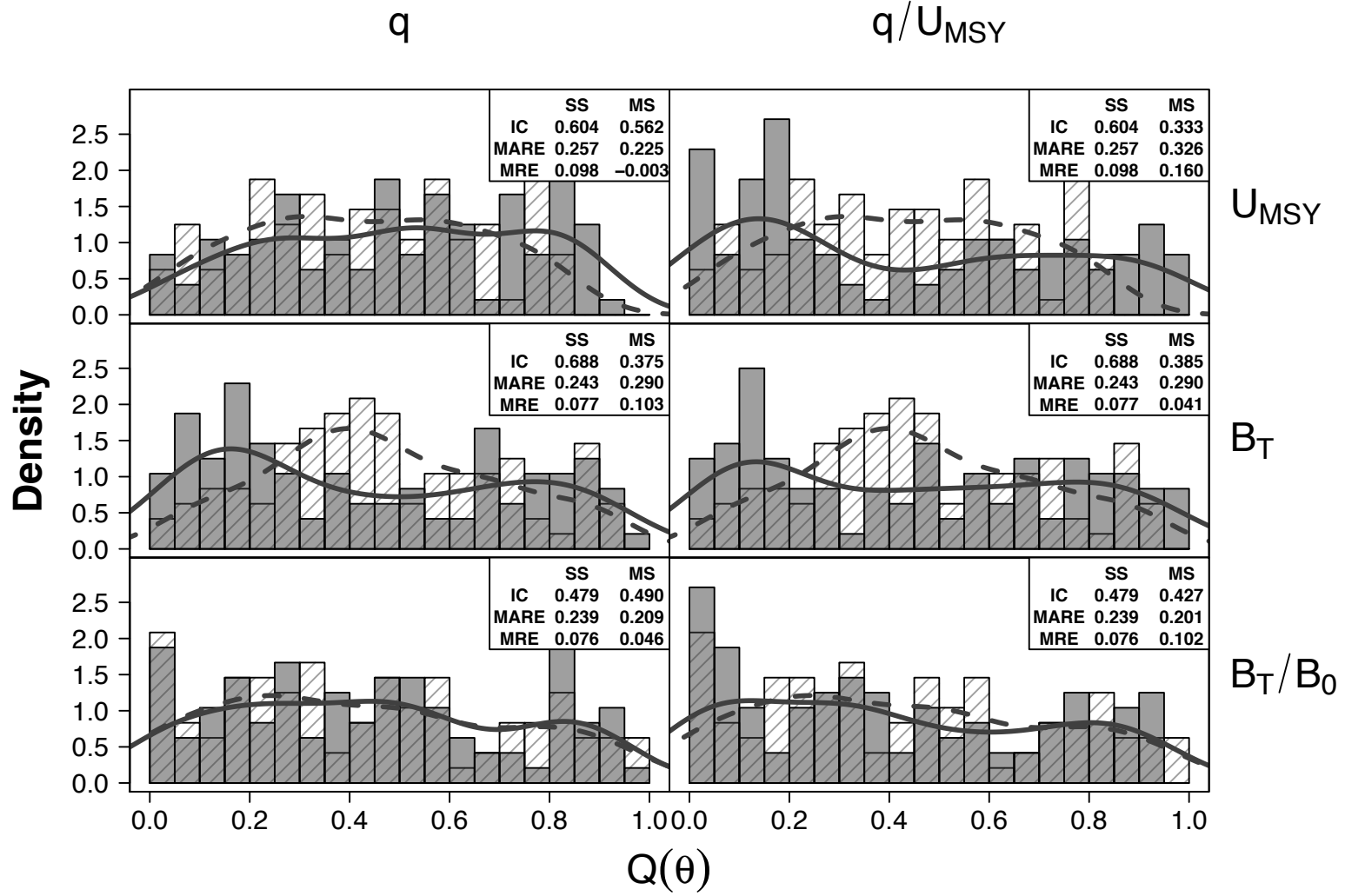


Figure 7: Density of predictive quantiles $Q(\theta)$ for estimates of key management parameters (rows) from single stock and q and q/U_{MSY} hierarchical multi-stock model configuration, fit to 4 identical stock under a 1-way trip fishing history over a long time-series of observations, initialised at unfished ($L = 0$). Bars show probability density of Q distributions, with lines showing the kernel smoothed density for easier comparison between single stock (crosshatched bars and broken line) and multi-stock (dark grey bars and solid line). Top right hand corners of each panel show interval coverage (IC), median absolute relative error (MARE), and median relative error (MRE) for single stock (SS) and multi-stock models (MS).

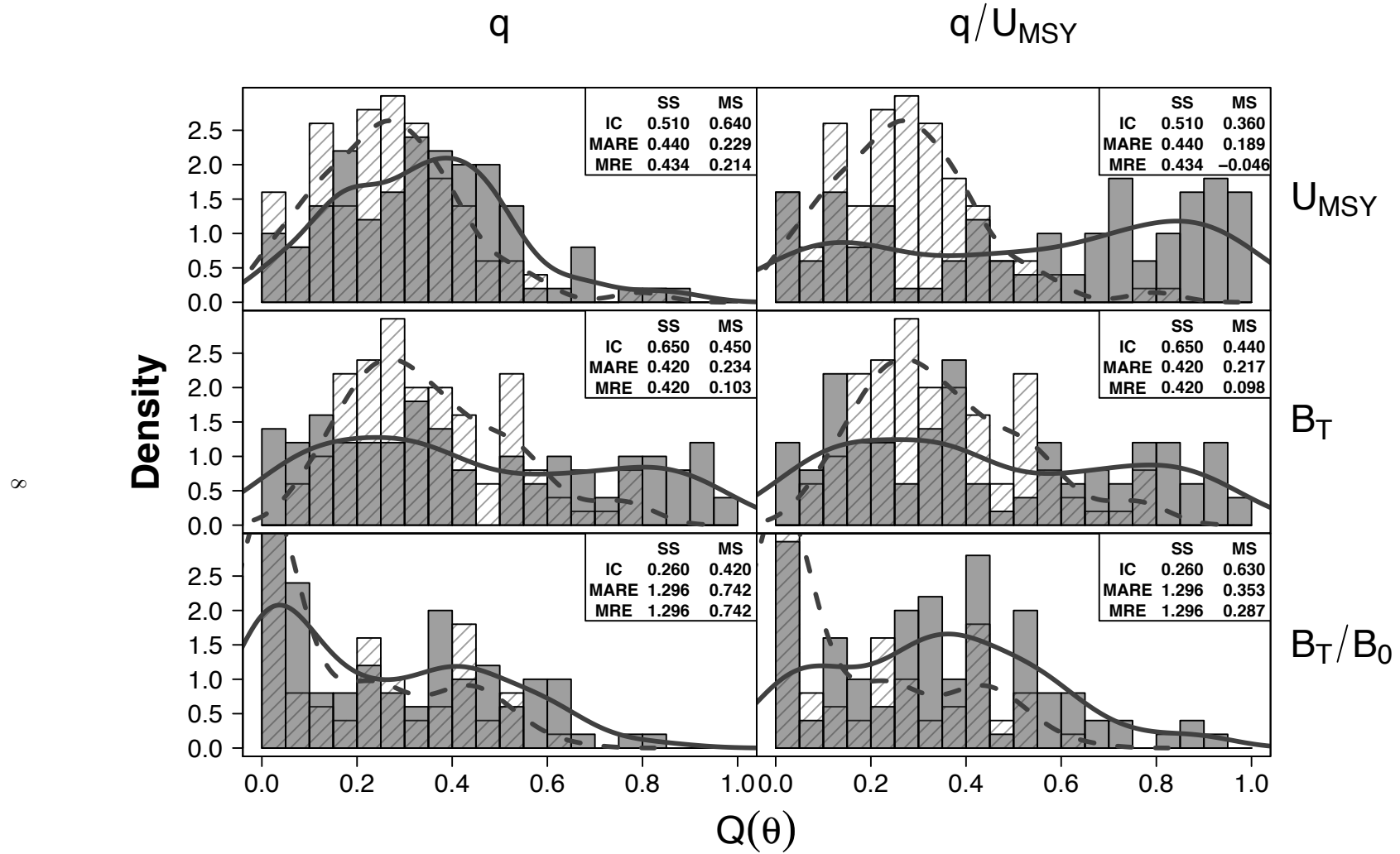


Figure 8: Density of predictive quantiles $Q(\theta)$ for estimates of key management parameters (rows) from single stock and q and q/U_{MSY} hierarchical multi-stock model configurations fit to a complex of four stocks with a 2-way trip fishing history with one low data quality stock ($L = 1$), which had a short time series of observations and was initialised at 40% of unfished. Bars show probability density of Q distributions, with lines showing the kernel smoothed density for easier comparison between single stock (crosshatched bars and broken line) and multi-stock (dark grey bars and solid line) models. Top right hand corners of each panel show interval coverage (IC), median absolute relative error (MARE), and median relative error (MRE) for single stock (SS) and multi-stock models (MS).

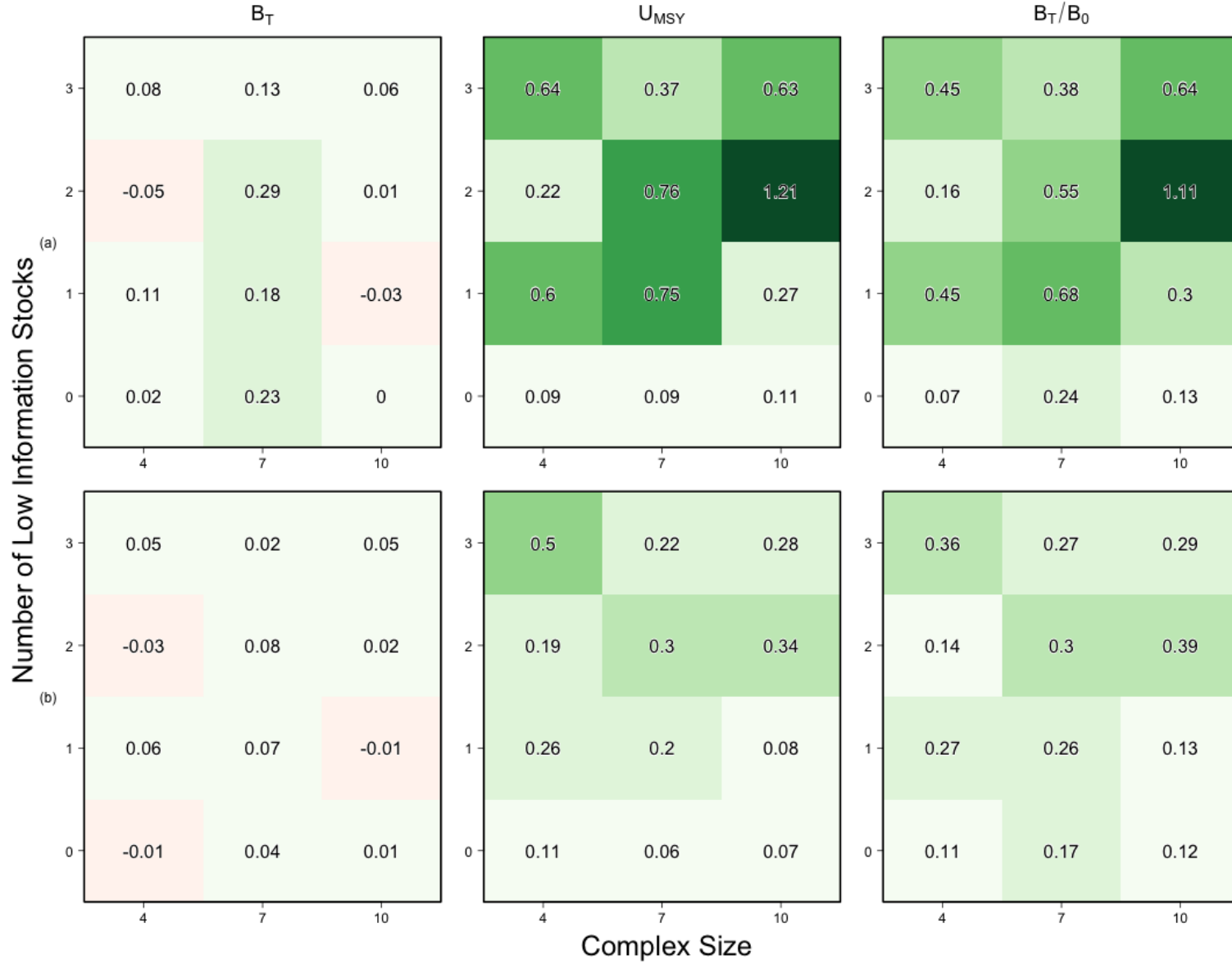


Figure 9: Response surface plots of (a) $\Delta(\theta_s) = \frac{MARE_{MS}(\theta)}{MARE_{SS}(\theta)} - 1$ and (b) $\bar{\Delta}(\theta) = \frac{\sum_s MARE_{MS}(\theta_s)}{\sum_s MARE_{SS}(\theta_s)} - 1$ values for $B_{1,T}$ (col. 1) and $U_{1,MS}$ (col. 2) and $B_{1,T}/B_{1,0}$ (col. 3). Surfaces are plotted as responses to complex size S along the horizontal axis, and number of low information stocks L along the vertical axis. Colours represent the magnitude of the response value, with higher absolute values showing more saturation than absolute values closer to 0, and hue changing from red to green as responses pass from negative, indicating that the single stock performs better, to positive, indicating that the multi-stock model performs better. Response values in each cell are the mean response values for all experimental treatments where S and L took the corresponding values along the axes. The full colour figure is available in the online version of the article.

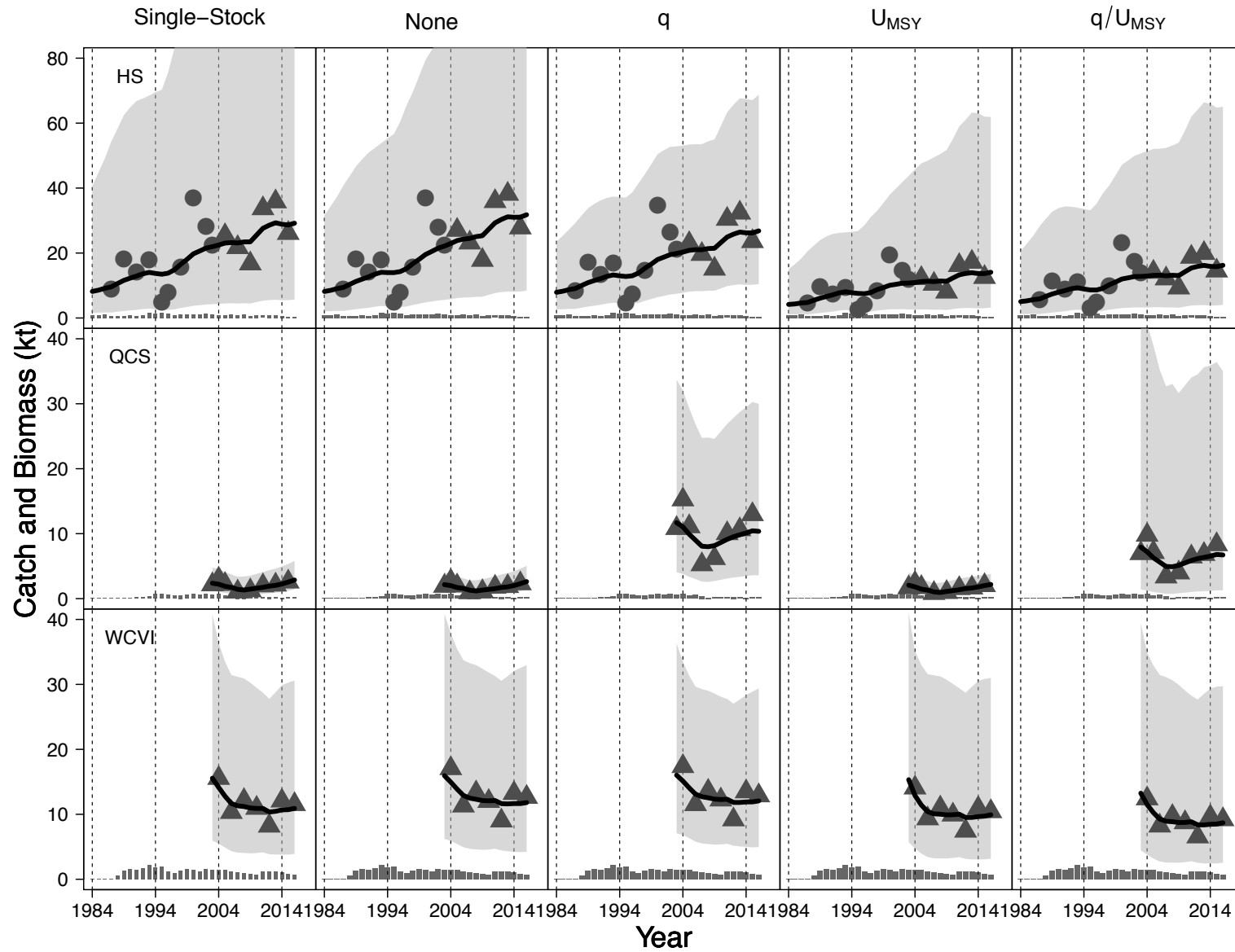


Figure 10: Estimated biomass time series for all three Dover Sole stocks. Estimates were produced by the single-stock and 4 top scoring multi-stock assessment model configurations under the low process error variance hypothesis. Grey regions indicate 95% confidence intervals around the maximum likelihood estimates, indicated by the black lines. Black vertical bars at the bottom of each plot show absolute landings and discards. Points indicate survey biomass data scaled by estimated catchability. Circular data points indicate Survey 1 (HS only), while triangular points indicate Survey 2.